

Задача 1.А.



(1)  $\begin{cases} mg = N + mg \frac{t}{c} \sin \alpha \\ mg \frac{t}{c} \cos \alpha - \mu N = ma \end{cases}$

из (1), (2):  $a = g \left( \frac{t}{c} (\cos \alpha + \mu \sin \alpha) - \mu \right)$

$t_0 = \hat{c} \cdot \frac{\mu}{\cos \alpha + \mu \sin \alpha}$  - время начала движения.

$N=0 \rightarrow mg = mg \frac{t}{c} \sin \alpha \rightarrow t_1 = \frac{\hat{c}}{\sin \alpha}$  - время остановки

$$\Delta t = t_1 - t_0 = \hat{c} \left( \frac{\cos \alpha}{\sin^2 \alpha + \mu + \cos \alpha \sin \alpha} \right)$$

б)

$$a(t) = a(t' + t_0) = g \left( \frac{t'}{c} (\cos \alpha + \mu \sin \alpha) \right)$$

$$v(t') = \int_0^{t'} a(t') dt'$$

$$L = \int_0^{t'} v(t') dt' = \frac{g (\cos \alpha + \mu \sin \alpha)}{\hat{c}} \cdot \frac{t^3}{6}$$

22

Задача 15

$$a) \quad PV^n = \text{const} \Rightarrow \frac{dP}{P} + n \frac{dV}{V} = 0$$

$$\delta Q = dU + \delta A = \frac{i}{2} R dT + P dV$$

$$PV = \nu RT \rightarrow P dV + dPV = \nu R dT$$

$$\delta Q = P dV + \frac{i}{2} (P dV + dPV) = P dV \left( 1 + \frac{i}{2} - n \right)$$

$$1 + \frac{i}{2} > n \Rightarrow \boxed{n > \frac{i+2}{2} = \frac{7}{2}}$$

b)

$$P dV - n P dV = \nu R dT$$

$$dV P (1-n) = \nu R dT$$

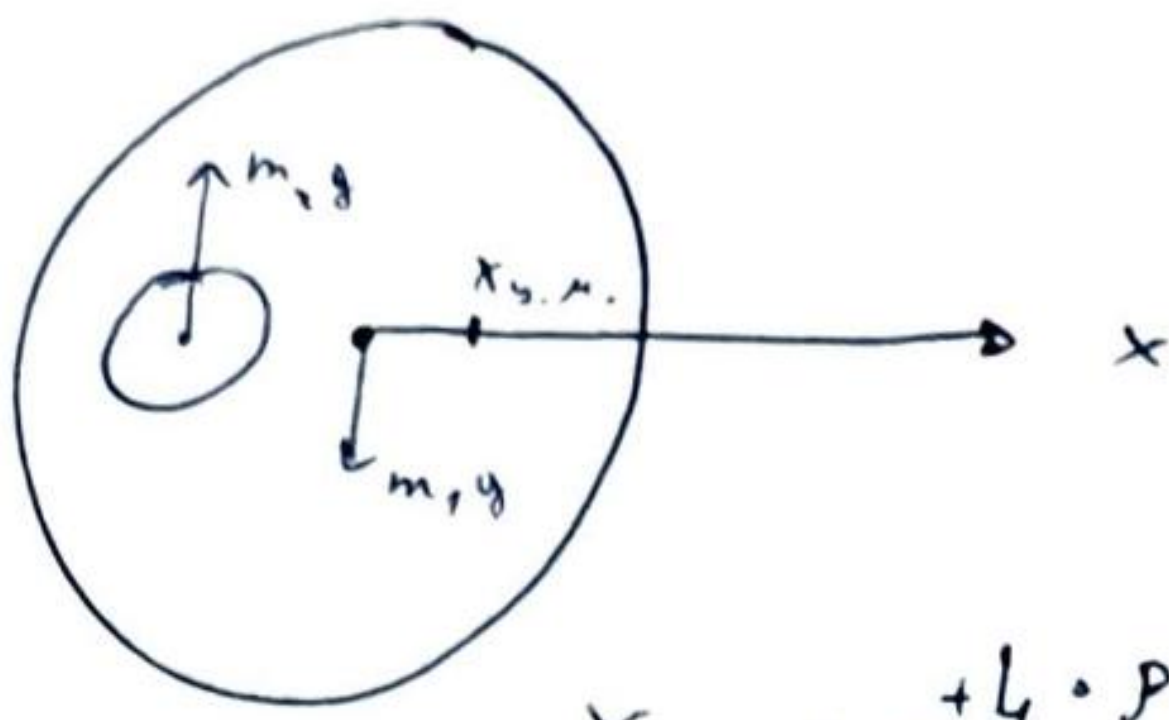
$$1-n > 0$$

$$\boxed{n < 1}$$



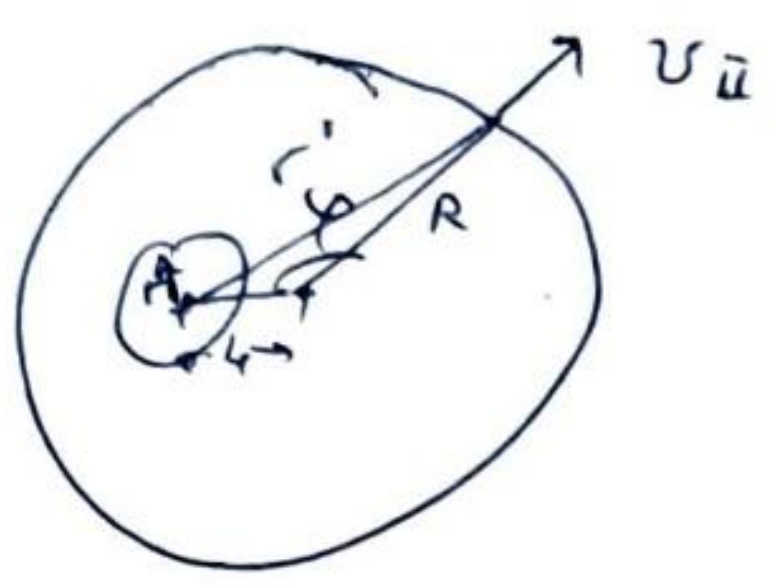
Задача 12

a)



$$x_{y.c.} = \frac{+L \cdot \rho = \frac{4}{3}\pi r^3}{\rho \frac{4}{3}\pi (R^3 - r^3)} = \boxed{L \frac{r^3}{R^3 - r^3}}$$

b)



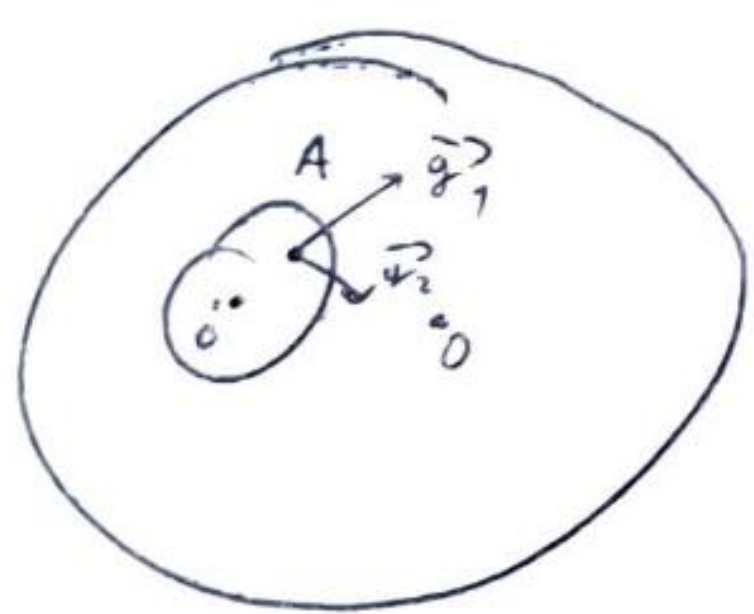
$$r'^2 = R^2 + L^2 - 2RL \cos \varphi$$

$$\frac{m v_{\bar{u}}^2}{2} - G \frac{m}{R} \rho \frac{4}{3}\pi R^3 + G \frac{m}{r'} \rho \frac{4}{3}\pi r^3 = 0.$$

$$v_{\bar{u}} = \sqrt{\frac{8}{3}\pi \rho G \left( R^2 - \frac{r^3}{r'} \right)}$$

$$r' = \sqrt{R^2 + L^2 - 2RL \cos \varphi}$$

c)



$$\begin{cases} \vec{y}_1 = -4\pi G \rho \frac{\vec{O'A}}{3} \\ \vec{y}_2 = +4\pi G \rho \frac{\vec{O'A}}{3} \end{cases} \Rightarrow \vec{y}_1 + \vec{y}_2 = \frac{4\pi G \rho L}{3} = g_0.$$

$$\frac{g_0 t^2}{2} = 2r$$

$$t = \sqrt{\frac{4r - 3}{4\pi G \rho L}} = \sqrt{\frac{3r}{\pi G \rho L}}$$



23 *zayon*

a)

$$\frac{d\varphi}{dt} = \dot{I} R = \frac{d(B \cdot L v \cos \theta)}{dt} = BL v \cos \theta$$

$$\boxed{\dot{I} = 0}$$

b)



$$F_x = mg \sin \theta$$

c)

~~not~~ no probability problem given:



g)

$$F = mg \sin \theta = BL \dot{I} = BL \cdot \frac{BL v_0 \cos \theta}{R}$$

$$\boxed{v_0 = \frac{mg \sin \theta R}{(BL)^2}}$$

e)

$$mg \sin \theta - \frac{(BL)^2}{R} \cos \theta v = m \frac{dv}{dt}$$

$$1 - \frac{v}{v_0} = \frac{dv}{dt} \cdot \frac{1}{g \sin \theta}$$

$$\boxed{v = v_0 \left( 1 - e^{-\frac{g \sin \theta t}{v_0}} \right)}$$