



# A. Earth as a blackbody

A-1. All the energy emitted from the surface of the Sun, will reach a sphere of radius d, therefore:

$$\sigma T_{\rm S}^4. (4\pi R_{\rm S}^2) = (4\pi d^2). S_0$$

$$S_0 = \sigma T_{\rm S}^4. \left(\frac{R_{\rm S}}{d}\right)^2 = 5.67 \times 10^{-8} \frac{\rm W}{\rm m^2 K^4} \times (5.77 \times 10^3 \,\rm K)^4 \times \left(\frac{6.96 \times 10^8 \,\rm m}{1.5 \times 10^{11} \,\rm m}\right)^2 = 1.35 \times 10^3 \frac{\rm W}{\rm m^2}$$

$$A-1 (0.6 \,\rm pt)$$

$$S_0 = \sigma T_{\rm S}^4. \left(\frac{R_{\rm S}}{d}\right)^2 , \text{ Numerical value of } S_0 = 1.35 \times 10^3 \,\rm W/m^2$$

A-2. It is assumed that the Earth is in thermal equilibrium. Therefore, the energy it receives per unit time should be equal to the energy it radiates per unit time. The Earth's cross-section intercepting the solar radiation at this distance has an area of  $\pi R_E^2$ , but the Earth radiates heat from all points on its surface with an area of  $4\pi R_E^2$ , so:

$$\pi R_{\rm E}^2 S_0 = 4\pi R_{\rm E}^2 \sigma T_{\rm E}^4 \quad \rightarrow T_{\rm E} = \left(\frac{S_0}{4\sigma}\right)^{\frac{1}{4}} = 278 \text{ K}$$

A-2 (0.6 pt)  

$$T_{\rm E} = \left(\frac{S_0}{4\sigma}\right)^{\frac{1}{4}} = \sqrt{\frac{R_{\rm S}}{2d}}T_{\rm S} \qquad , \text{Numerical value of } T_{\rm E} = 278 \text{ K}$$

A-3. The radiation is maximum at the wavelength for which the derivative of u with respect to  $\lambda$  is zero:

$$\frac{du}{d\lambda} = \frac{2\pi hc^2}{\lambda^6} \cdot \frac{1}{exp(\frac{hc}{\lambda k_{\rm B}T}) - 1} \cdot \left[ -5 + \frac{hc}{\lambda k_{\rm B}T} \frac{exp(\frac{hc}{\lambda k_{\rm B}T})}{exp(\frac{hc}{\lambda k_{\rm B}T}) - 1} \right]$$
$$\frac{du}{d\lambda}|_{\lambda=\lambda_{\rm m}} = 0 \quad \Rightarrow \quad \frac{hc}{\lambda_{\rm m}k_{\rm B}T} \frac{exp\left(\frac{hc}{\lambda_{\rm m}k_{\rm B}T}\right)}{exp\left(\frac{hc}{\lambda_{\rm m}K_{\rm B}T}\right) - 1} = 5$$

Defining  $x_{\rm m} \equiv \frac{hc}{\lambda_{\rm m}k_{\rm B}T}$  we obtain the following transcendental equation:

$$5(1 - e^{-x_{\rm m}}) - x_{\rm m} = 0$$





A-3 (0.4 pt)  $f(x) = 5(1 - e^{-x}) - x$ 

A-4. The first guess is  $x_m^{(1)} = 5$ . Substituting repeatedly for  $x_m$  we can continue as follows:

$$x_{\rm m}^{(2)} = 5(1 - e^{-5}) = 4.97$$
  
 $x_{\rm m}^{(3)} = 5(1 - e^{-4.97}) = 4.97$ 

Further iterations do not change the value of  $x_m$  to three significant figures, so:

$$\lambda_{\rm m} T = \frac{hc}{x_{\rm m} k_{\rm B}} = b = 1240 \text{ eV} \cdot \text{nm} \times \frac{1}{4.97 \times 8.62 \times 10^{-5} \text{ eVK}^{-1}} = 2.89 \times 10^{6} \text{ nm} \cdot \text{K}$$

$$\overline{\text{A-4 (0.4 pt)}}$$

$$x_{\rm m} = \{4.96, 4.97\}$$
, Numerical value of  $b = [2.89, 2.90] \times 10^{6} \text{ nm} \cdot \text{K}$ 

A-5. Using Wien's displacement law and the constant *b* obtained in the previous part, we can calculate the wavelength at which the radiation from the Sun and the Earth reaches its maximum:

$$\lambda_{\max}^{\text{Sun}} = \frac{b}{T_{\text{S}}} = \frac{2.89 \times 10^{6} \text{ nm} \cdot \text{K}}{5.77 \times 10^{3} \text{ K}} = [5.01, 5.02] \times 10^{2} \text{ nm}$$
$$\lambda_{\max}^{\text{Earth}} = \frac{b}{T_{\text{E}}} = \frac{2.89 \times 10^{6} \text{ nm} \cdot \text{K}}{278 \text{ K}} = 1.04 \times 10^{4} \text{ nm}$$

A-5 (0.2 pt)  $\lambda_{\text{max}}^{\text{Sun}} = [5.01, 5.02] \times 10^2 \text{ nm}$ ,  $\lambda_{\text{max}}^{\text{Earth}} = 1.04 \times 10^4 \text{ nm}$ 

A-6. From the diagram, it can clearly be seen that  $\gamma \tilde{u}_{S}(\lambda_{\max}^{S}) = u(\lambda_{\max}^{Earth}, T_{E})$ , so we have:

$$\tilde{u}_{\rm S}\left(\lambda_{\rm max}^{\rm Sun}\right) = \left(\frac{R_{\rm S}}{d}\right)^2 \frac{2\pi hc^2}{\left(\lambda_{\rm max}^{\rm Sun}\right)^5} \frac{1}{exp\left(\frac{hc}{\lambda_{\rm max}^{\rm Sun}k_{\rm B}T_{\rm S}}\right) - 1} = \left(\frac{R_{\rm S}}{d}\right)^2 \frac{2\pi hc^2}{\left(\lambda_{\rm max}^{\rm Sun}\right)^5} \frac{1}{exp\left(\frac{hc}{k_{\rm B}b}\right) - 1}$$

$$u(\lambda_{\max}^{\text{Earth}}, T_{\text{E}}) = \frac{2\pi hc^2}{\left(\lambda_{\max}^{\text{Earth}}\right)^5} \frac{1}{exp\left(\frac{hc}{\lambda_{\max}^{\text{Earth}}k_{\text{B}}T_{\text{E}}}\right) - 1} = \frac{2\pi hc^2}{\left(\lambda_{\max}^{\text{Earth}}\right)^5} \frac{1}{exp\left(\frac{hc}{k_{\text{B}}b}\right) - 1}$$

Dividing these two quantities we'll find:





$$\gamma = \left(\frac{d}{R_{\rm S}}\right)^2 \times \left(\frac{T_{\rm E}}{T_{\rm S}}\right)^5 = [1.20, 1.21] \times 10^{-2}$$

A-6 (0.8 pt)  

$$\gamma = \left(\frac{d}{R_{\rm S}}\right)^2 \times \left(\frac{T_{\rm E}}{T_{\rm S}}\right)^5 = \left(\frac{d}{R_{\rm S}}\right)^2 \times \left(\frac{\lambda_{\rm max}^{\rm Sun}}{\lambda_{\rm max}^{\rm Earth}}\right)^5 \quad , \text{ Numerical value of } \gamma = [1.20, 1.21] \times 10^{-2}$$

# B. The Greenhouse Effect

B-1. Both the Earth and its atmosphere are in thermal equilibrium, so one can write an equation that balances the input and output powers. For the Earth we have:

$$(\pi R_{\rm E}^2)(1-r_{\rm A})S_0 + (4\pi R_{\rm E}^2)\sigma T_{\rm A}^4 = (4\pi R_{\rm E}^2)\sigma T_{\rm E}^4,$$

and for the atmosphere:

$$(4\pi R_{\rm E}^2)\sigma T_{\rm E}^4 = 2(4\pi R_{\rm E}^2)\sigma T_{\rm A}^4.$$

Note that the coefficient 2 on the right-hand side of the equation is due to the atmosphere radiating heat on both sides (above and below). Eliminating  $T_E$  from the two relations we obtain:

$$T_{\rm A} = \left(\frac{(1-r_{\rm A})\frac{S_0}{4}}{\sigma}\right)^{\frac{1}{4}} = 2.58 \times 10^2 \text{ K} \qquad \Rightarrow \quad T_{\rm E} = (2T_{\rm A}^4)^{\frac{1}{4}} = 3.07 \times 10^2 \text{ K}$$

B-1 (1.0 pt)  

$$T_{\rm A} = \left(\frac{(1-r_{\rm A})\frac{S_0}{4}}{\sigma}\right)^{\frac{1}{4}}$$
, Numerical value of  $T_{\rm A} = 2.58 \times 10^2$  K  

$$T_{\rm E} = \left(\frac{(1-r_{\rm A})\frac{S_0}{2}}{\sigma}\right)^{\frac{1}{4}}$$
, Numerical value of  $T_{\rm E} = 3.07 \times 10^2$  K

B-2. As can be seen in the figure, a fraction  $(1 - r_A)$  of the solar radiation reaches the Earth's surface after traversing the atmosphere. A fraction  $r_E$  of this light is reflected back and reaches the atmosphere, where a fraction  $r_A$  is reflected and returns to the Earth's surface. This process repeats *ad infinitum* and the sum of the powers transmitted at all these instances, determines the albedo. Denoting the power returned to space after *n* reflections by  $\tilde{S}_n$ , we'll have  $\tilde{S}_0 = r_A S_0$  and





the remaining power i.e.  $(1 - r_A)S_0$ , reaches the Earth's surface. From this power,  $(1 - r_A)r_ES_0$  is reflected, and a fraction  $1 - r_A$  of it is transmitted through the atmosphere to the space, hence:

$$\tilde{S}_1 = (1 - r_A)^2 r_E S_0 = \frac{(1 - r_A)^2}{r_A} r_E \tilde{S}_0$$

The power that is reflected back to the Earth by the atmosphere after (n-1) reflections is  $\tilde{S}_{n-1}\left(\frac{r_A}{1-r_A}\right)$ , of which a fraction  $r_E$  is again sent back towards the atmosphere on the *n*'th reflection, and the atmosphere allows a fraction  $1 - r_A$  of this reflected power to escape into the space, thus:

$$\tilde{S}_n = \frac{\tilde{S}_{n-1}}{1 - r_A} r_A r_E \times (1 - r_A) = r_A r_E \tilde{S}_{n-1} = (r_A r_E)^{n-1} \tilde{S}_1$$

By adding all these terms, one obtains the power returned per unit area from the Earth-atmosphere system:

$$\begin{split} \tilde{S} &= \sum_{n=0}^{\infty} \tilde{S}_n = \tilde{S}_0 + \tilde{S}_1 \sum_{n=1}^{\infty} (r_A r_E)^{n-1} = r_A S_0 + (1 - r_A)^2 r_E S_0 \times \frac{1}{1 - r_A r_E} \\ &= \left[ r_A + \frac{(1 - r_A)^2 r_E}{1 - r_A r_E} \right] \times S_0 \end{split}$$

Dividing by the solar constant we get the value for albedo:

$$\alpha = \frac{\tilde{S}}{S_0} = r_{\rm A} + \frac{(1 - r_{\rm A})^2 r_{\rm E}}{1 - r_{\rm A} r_{\rm E}} = 3.13 \times 10^{-1}$$

B-2 (1.6 pt)  

$$\alpha = r_{\rm A} + \frac{(1-r_{\rm A})^2 r_{\rm E}}{1-r_{\rm A} r_{\rm E}} , \text{ Numerical value of } \alpha = 3.13 \times 10^{-1}$$

B-3. Again, thermal equilibrium requires the input and output powers to be equal both for the Earth and for the atmosphere, the only difference being that the Earth absorbs now a fraction  $1 - \alpha$  of the Sun's radiation. Thus, for Earth we have:

$$(4\pi R_{\rm E}^2)\epsilon\sigma T_{\rm A}^4 + (\pi R_{\rm E}^2)(1-\alpha)S_0 = (4\pi R_{\rm E}^2)\sigma T_{\rm E}^4,$$

and for the atmosphere:

$$(4\pi R_{\rm E}^2)\epsilon\sigma T_{\rm E}^4 = 2(4\pi R_{\rm E}^2)\epsilon\sigma T_{\rm A}^4$$
$$T_{\rm E} = \left[\frac{(1-\alpha)}{2\sigma(2-\epsilon)}S_0\right]^{\frac{1}{4}} , \qquad T_{\rm A} = \left(\frac{T_{\rm E}^4}{2}\right)^{\frac{1}{4}}$$



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$$\epsilon = \frac{\left[\sigma T_{\rm E}^4 - \frac{(1-\alpha)}{4}S_0\right]}{\sigma T_{\rm A}^4} = 2\frac{\left[\sigma T_{\rm E}^4 - \frac{(1-\alpha)}{4}S_0\right]}{\sigma T_{\rm E}^4} = [8.07, 8.11] \times 10^{-1}$$

B-3 (1.0 pt)  

$$T_{\rm E} = \left[\frac{(1-\alpha)}{2\sigma(2-\epsilon)}S_0\right]^{\frac{1}{4}}$$
, Numerical value of  $\epsilon = [8.07, 8.11] \times 10^{-1}$ 

B-4.

$$\frac{dT_{\rm E}}{d\epsilon} = \frac{1}{4} \left[ \frac{(1-\alpha)S_0}{2\sigma(2-\epsilon)} \right]^{\frac{1}{4}} \frac{1}{(2-\epsilon)}$$

$$dT_{\rm E} = \frac{dT_{\rm E}}{d\epsilon} \epsilon \frac{d\epsilon}{\epsilon} = \left[\frac{4\sigma T_{\rm E}^4}{(1-\alpha)S_0} - 1\right] \frac{T_{\rm E}}{4} \times 0.01 = [4.87, 4.92] \times 10^{-1}$$

B-4 (0.8pt)  
$$\frac{dT_{\rm E}}{d\epsilon} = \frac{1}{4} \left[ \frac{(1-\alpha)S_0}{2\sigma(2-\epsilon)} \right]^{\frac{1}{4}} \frac{1}{(2-\epsilon)} \qquad , \text{Numerical value of } \delta T_{\rm E} = [4.87, 4.92] \times 10^{-1} \text{ K}$$

B-5. The equations for thermal equilibrium are similar to those for Part B.3, only a non-radiative thermal current needs to be added. For the Earth:

$$(\pi R_{\rm E}^2)(1-\alpha)S_0 + (4\pi R_{\rm E}^2)\epsilon\sigma T_{\rm A}^4 = (4\pi R_{\rm E}^2)\sigma T_{\rm E}^4 + (4\pi R_{\rm E}^2)k(T_{\rm E}-T_{\rm A}),$$

and for the atmosphere:

$$(4\pi R_{\rm E}^2)\epsilon\sigma T_{\rm E}^4 + (4\pi R_{\rm E}^2)k(T_{\rm E} - T_{\rm A}) = 2(4\pi R_{\rm E}^2)\epsilon\sigma T_{\rm A}^4.$$

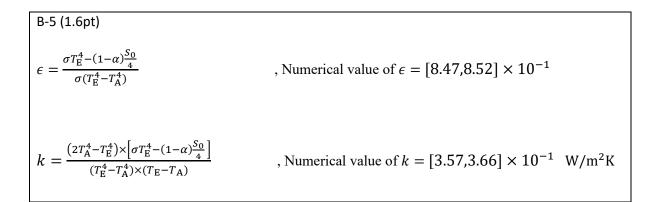
After completing the calculations, we will have:

$$\epsilon = \frac{\sigma T_{\rm E}^4 - (1 - \alpha) \frac{S_0}{4}}{\sigma (T_{\rm E}^4 - T_{\rm A}^4)} = [8.47, 8.52] \times 10^{-1}$$

$$k = \frac{\epsilon \sigma (2T_{\rm A}^4 - T_{\rm E}^4)}{T_{\rm E} - T_{\rm A}} = \frac{(2T_{\rm A}^4 - T_{\rm E}^4) \times \left[\sigma T_{\rm E}^4 - (1 - \alpha) \frac{S_0}{4}\right]}{(T_{\rm E}^4 - T_{\rm A}^4) \times (T_{\rm E} - T_{\rm A})} = [3.57, 3.66] \times 10^{-1} \,\text{W/m}^2\text{K}$$







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B-6. In order to find the change in the temperatures of the Earth and the atmosphere in terms of  $\epsilon$  and k, we take the logarithm of both sides of the relations before taking the derivative:

$$\begin{split} \ln \epsilon &= \ln \left[ \sigma T_{\rm E}^4 - (1-\alpha) \frac{S_0}{4} \right] - \ln \sigma - \ln \left( T_{\rm E}^4 - T_{\rm A}^4 \right) \\ \ln k &= \ln \epsilon + \ln \sigma + \ln (2T_{\rm A}^4 - T_{\rm E}^4) - \ln (T_{\rm E} - T_{\rm A}) \\ \frac{1}{\epsilon} &= \frac{4\sigma T_{\rm E}^3 \frac{dT_{\rm E}}{d\epsilon}}{\sigma T_{\rm E}^4 - (1-\alpha) \frac{S_0}{4}} - \frac{4T_{\rm E}^3 \frac{dT_{\rm E}}{d\epsilon} - 4T_{\rm A}^3 \frac{dT_{\rm A}}{d\epsilon}}{T_{\rm E}^4 - T_{\rm A}^4} \\ 0 &= \frac{1}{\epsilon} + \frac{8T_{\rm A}^3 \frac{dT_{\rm A}}{d\epsilon} - 4T_{\rm E}^3 \frac{dT_{\rm E}}{d\epsilon}}{2T_{\rm A}^4 - T_{\rm E}^4} - \frac{dT_{\rm E}}{\sigma T_{\rm E}^4 - T_{\rm A}^4} \\ \epsilon \left[ \frac{1}{T_{\rm E} - T_{\rm A}} + \frac{4T_{\rm E}^3}{2T_{\rm A}^4 - T_{\rm E}^4} \right] \frac{dT_{\rm E}}{d\epsilon} = 1 + \epsilon \left[ \frac{8T_{\rm A}^3}{2T_{\rm A}^4 - T_{\rm E}^4} + \frac{1}{T_{\rm E} - T_{\rm A}} \right] \frac{dT_{\rm A}}{d\epsilon} \\ 1 + \epsilon \left[ \frac{4T_{\rm E}^3}{T_{\rm E}^4 - T_{\rm A}^4} - \frac{4\sigma T_{\rm E}^3}{\sigma T_{\rm E}^4 - (1-\alpha) \frac{S_0}{4}} \right] \frac{dT_{\rm E}}{d\epsilon} = \frac{4T_{\rm A}^3}{T_{\rm E}^4 - T_{\rm A}^4} \epsilon \frac{dT_{\rm A}}{d\epsilon} \end{split}$$

Solving this set of linear equations and substituting  $\epsilon$  in B-5, we find:





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$$\begin{split} \frac{dT_{\rm E}}{d\epsilon} &= \frac{\left[\frac{\sigma(T_{\rm E}^4 - T_{\rm A}^4)}{\sigma T_{\rm E}^4 - (1 - \alpha)\frac{S_0}{4}}\right] \left[1 + \left(\frac{T_{\rm E}^4 - T_{\rm A}^4}{4T_{\rm A}^3}\right) \left[\frac{8T_{\rm A}^3}{2T_{\rm A}^4 - T_{\rm E}^4} + \frac{1}{T_{\rm E} - T_{\rm A}}\right]\right]}{\left[\frac{1}{T_{\rm E} - T_{\rm A}} + \frac{4T_{\rm E}^3}{2T_{\rm A}^4 - T_{\rm E}^4}\right] - \left(\frac{\sigma T_{\rm A}^4 - (1 - \alpha)\frac{S_0}{4}}{\sigma T_{\rm E}^4 - (1 - \alpha)\frac{S_0}{4}}\right) \left(\frac{T_{\rm E}}{T_{\rm A}}\right)^3 \left[\frac{8T_{\rm A}^3}{2T_{\rm A}^4 - T_{\rm E}^4} + \frac{1}{T_{\rm E} - T_{\rm A}}\right]}{\left[\frac{1}{T_{\rm E} - T_{\rm A}} + \frac{4T_{\rm E}^3}{2T_{\rm A}^4 - T_{\rm E}^4}\right] - \left(\frac{\sigma T_{\rm A}^4 - (1 - \alpha)\frac{S_0}{4}}{\sigma T_{\rm E}^4 - (1 - \alpha)\frac{S_0}{4}}\right) \left(\frac{T_{\rm E}}{T_{\rm A}}\right)^3 \left[\frac{8T_{\rm A}^3}{2T_{\rm A}^4 - T_{\rm E}^4} + \frac{1}{T_{\rm E} - T_{\rm A}}\right]}{\left[\frac{1}{T_{\rm E} - T_{\rm A}} + \frac{4T_{\rm E}^3}{2T_{\rm A}^4 - T_{\rm E}^4}\right] - \left(\frac{\sigma T_{\rm A}^4 - (1 - \alpha)\frac{S_0}{4}}{\sigma T_{\rm E}^4 - (1 - \alpha)\frac{S_0}{4}}\right) \left(\frac{T_{\rm E}}{T_{\rm A}}\right)^3 \left[\frac{8T_{\rm A}^3}{2T_{\rm A}^4 - T_{\rm E}^4} + \frac{1}{T_{\rm E} - T_{\rm A}}\right]}{dT_{\rm E} = \epsilon \frac{dT_{\rm E}}{d\epsilon} \frac{d\epsilon}{\epsilon} = [5.21, 5.28] \times 10^{-1} \,\rm K\end{split}$$

$$\begin{array}{l} \text{B-6 (1.0pt)} \\ \text{(a)} & \begin{cases} \epsilon \left[ \frac{1}{T_{\text{E}} - T_{\text{A}}} + \frac{4T_{\text{E}}^{3}}{2T_{\text{A}}^{4} - T_{\text{E}}^{4}} \right] \frac{dT_{\text{E}}}{d\epsilon} = 1 + \epsilon \left[ \frac{8T_{\text{A}}^{3}}{2T_{\text{A}}^{4} - T_{\text{E}}^{4}} + \frac{1}{T_{\text{E}} - T_{\text{A}}} \right] \frac{dT_{\text{A}}}{d\epsilon} \\ 1 + \epsilon \left[ \frac{4T_{\text{E}}^{3}}{T_{\text{E}}^{4} - T_{\text{A}}^{4}} - \frac{4\sigma T_{\text{E}}^{3}}{\sigma T_{\text{E}}^{4} - (1 - \alpha) \frac{S_{0}}{4}} \right] \frac{dT_{\text{E}}}{d\epsilon} = \frac{4T_{\text{A}}^{3}}{T_{\text{E}}^{4} - T_{\text{A}}^{4}} \epsilon \frac{dT_{\text{A}}}{d\epsilon} \end{cases} \\ \text{(b) } \delta T_{\text{E}} = [5.21, 5.28] \times 10^{-1} \text{ K} \end{cases}$$





# A: Paul Trap

A-1. Due to the symmetry, on the *z*-axis the only non-zero component of electric field is in the *z*-direction. So:

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$$\vec{E}(0,0,z) = E_z(0,0,z) \,\hat{z} = \hat{z} \,\int \frac{dq}{4\pi\epsilon_0} \frac{1}{(R^2 + z^2)} \times \frac{z}{(R^2 + z^2)^{\frac{1}{2}}}$$

The element dq is equal to  $\lambda R d\phi$  where  $\phi$  is the angle with the x-axis. Thus:

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$$E(0,0,z) = \hat{z} \int \frac{\lambda R d\phi}{4\pi\epsilon_0} \frac{z}{(z^2 + R^2)^{\frac{3}{2}}} = \hat{z} \frac{\lambda R}{2\epsilon_0} \frac{z}{(z^2 + R^2)^{\frac{3}{2}}}$$

For  $z \ll R$  this can be written as:

$$E_z(0,0,z) = \frac{\lambda R}{2\epsilon_0} \frac{z}{R^3} = \frac{\lambda z}{2\epsilon_0 R^2}$$

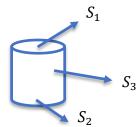
Very close to the *z*-axis, we can write:

$$E_z(x, y, z) = E_z(0, 0, z) + x \frac{\partial E_z}{\partial x}|_{(0, 0, z)} + y \frac{\partial E_z}{\partial y}|_{(0, 0, z)} + O(x^2, y^2, z^2)$$

Since, there is no difference between x and -x or y and -y, it turns out that  $\frac{\partial E_z}{\partial x} = \frac{\partial E_z}{\partial y} = 0$ . Thus, to the first order in x, y, and z we have:

$$E_z(x, y, z) = \frac{\lambda z}{2\epsilon_0 R^2}$$

Consider a Gaussian surface in the shape of a symmetric cylinder around the z-axis whose bases are parallel with the xy-plane. The cylinder's radius is  $\rho$  and its height is 2z both of which are small quantities. By Gauss's law we have:







$$0 = \frac{Q_{in}}{\epsilon_0} = \oint \vec{E} \cdot d\vec{S} = \int_{S_1} \vec{E} \cdot d\vec{S} + \int_{S_2} \vec{E} \cdot d\vec{S} + \int_{S_3} \vec{E} \cdot d\vec{S}$$

Integration over  $S_1$  and  $S_2$  gives:

$$\int_{S_1} \vec{E} \cdot d\vec{S} = \int_{S_2} \vec{E} \cdot d\vec{S} = \pi \rho^2 \times \frac{\lambda z}{2\epsilon_0 R^2}.$$

Integration over  $S_3$  involves the  $\rho$ -component for which we can write the following expansion:

$$E_{\rho}(z,\rho,\phi) = E_{\rho}(0,\rho,\phi) + z \frac{\partial E_{\rho}}{\partial z}|_{(0,\rho,\phi)} + O(z^2)$$

We have  $0 = \frac{\partial E_{\rho}}{\partial z}|_{(0,\rho,\phi)}$  due to symmetry between z and -z, hence,  $E_{\rho}(z,\rho,\phi) = E_{\rho}(0,\rho,\phi)$ up to the first order. Axial symmetry also implies  $\frac{dE_{\rho}}{d\phi} = 0$ . Consequently:

$$\int_{S_3} \vec{E} \cdot d\vec{S} = E_{\rho}(0,\rho,0) \times 2z \times 2\pi\rho$$

So, Gauss's law implies:

$$0 = E_{\rho} \times 4\pi z \rho + 2\pi \rho^2 \frac{\lambda z}{2\epsilon_0 R^2}$$

Therefore,  $E_{\rho}$  will be:

$$E_{\rho} = -\frac{\lambda \rho}{4\epsilon_0 R^2}$$

In the cylindrical coordinate we will have:

$$\vec{E}(\rho,\phi,z) = -\frac{\lambda\rho}{4\epsilon_0 R^2}\hat{\rho} + \frac{\lambda z}{2\epsilon_0 R^2}\hat{z}$$

In cartesian coordinates we will have:

$$\vec{E}(x, y, z) = \frac{\lambda}{4\epsilon_0 R^2} (-x, -y, 2z)$$

Since the ring is positively charged, the equilibrium in the x and y directions are stable, while the equilibrium in the z-direction is unstable. The equations of motion in the x and y directions read:

$$m\ddot{x} = qE_x = -\frac{q\lambda}{4\epsilon_0 R^2}x$$
$$m\ddot{y} = qE_y = -\frac{q\lambda}{4\epsilon_0 R^2}y$$





Therefore, the frequencies of small oscillations are:

$$\omega_x^2 = \omega_y^2 = \frac{q\lambda}{4\epsilon_0 R^2 m}$$

A-1 (1.5 pt)  
(a) 
$$\vec{E}(x, y, z) = \frac{-\lambda x}{4\epsilon_0 R^2} \hat{x} + \frac{-\lambda y}{4\epsilon_0 R^2} \hat{y} + \frac{\lambda z}{2\epsilon_0 R^2} \hat{z}$$
  
(b)  $\omega_x = \omega_y = \sqrt{\frac{Q\lambda}{4\epsilon_0 R^2 m}}$ 

### A-2.

The force in the *z*-direction is:

$$F_{z} = qE_{z} = \frac{Q\lambda z}{2\epsilon_{0}R^{2}} = \frac{Q}{2\epsilon_{0}R^{2}}\lambda_{0}z + \frac{Qu}{2\epsilon_{0}R^{2}}\cos\Omega t z$$

the equation of motion can thus be written as:

$$\ddot{z} = \left(\frac{Q\lambda_0}{2\epsilon_0 R^2 m} + \frac{Qu}{2\epsilon_0 R^2 m} \cos\Omega t\right) z$$

Therefore:

$$k = \sqrt{\frac{Q\lambda_0}{2\epsilon_0 R^2 m}} \qquad , \qquad a = \frac{Qu}{2\epsilon_0 R^2 m \Omega^2}$$

A-2 (0.4 pt)  $k = \sqrt{\frac{Q\lambda_0}{2R^2 r}}$ 

 $2\epsilon_0 R^2 m$ 

$$a = \frac{Qu}{2\epsilon_0 R^2 m \Omega^2}$$

A.3.

$$z = p(t) + q(t) \rightarrow \ddot{p} + \ddot{q} = (k^2 + a\Omega^2 \cos \Omega t)(p+q)$$

- 1. We are assuming that p is almost constant,  $\ddot{p} \simeq 0$ .
- 2. According to the assumptions  $k^2 \ll a\Omega^2$  and  $q \ll p$  we can ignore  $k^2$  in the first term on the right-hand side of the equation and q in the second term.

hence, the equation of motion can be simplified as follows:

$$\ddot{q} = pa\Omega^2 \cos \Omega t.$$





As we have assumed that p is a constant, the second derivative of q is just proportional to  $\cos \Omega t$  which gives:

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$$q = -pa\cos\Omega t + c_1t + c_2.$$

Since q is supposed to remain small,  $c_1$  must vanish. Also  $c_2 = 0$  because the mean value of q is supposed to remain zero. Therefore:

 $q = -pa\cos\Omega t$ 

A-3 (1.8 pt) (a)  $\ddot{q}(t) = pa\Omega^2 \cos \Omega t$ (b)  $q(t) = -pa \cos \Omega t$ 

A-4. Using the final result for q the equation of motion for p reads:

$$\ddot{p} + pa\Omega^2 \cos \Omega t = (k^2 + a\Omega^2 \cos \Omega t)(p - ap \cos \Omega t)$$

Which gives:

$$\ddot{p} = k^2 p - ak^2 p \cos \Omega t - a^2 \Omega^2 p \cos^2 \Omega t$$

Averaging over one period, we'll have:

$$\langle \cos \Omega t \rangle = 0$$
 ,  $\langle \cos^2 \Omega t \rangle = \frac{1}{2}$ 

and:

$$\ddot{p} = \left(k^2 - \frac{a^2 \Omega^2}{2}\right)p.$$

In order for the motion to be stable, the expression inside the parentheses should be negative, i.e.

$$\frac{a^2\Omega^2}{2} > k^2 \qquad \rightarrow \qquad \Omega > \sqrt{2}\frac{k}{a}$$

A-4 (1.5 pt)  
(a) 
$$\ddot{p}(t) = \left(k^2 - \frac{a^2 \Omega^2}{2}\right)p$$
  
(b)  $\Omega > \sqrt{2}\frac{k}{a}$ 

A.5. With the given data we have:





$$k = \sqrt{\frac{Q\lambda_0}{2\epsilon_0 R^2 m}} = 2 \times 10^5 \text{ rad/s}$$

$$a = 0.04 \quad \rightarrow \quad \Omega_{\min} = 7 \times 10^6 \text{ rad/s}$$

which is in the range of radio waves.

A-5 (0.4 pt)  $k = 2 \times 10^5$  rad/s  $\Omega_{\rm min} = 7 \times 10^6$  rad/s

# **B:** Doppler Cooling

B-1. From the uncertainty principle we know:

 $\Delta E \times \Delta t \simeq \hbar$ 

Here  $\Delta t$  is the time  $\tau$  and  $\Delta E = \hbar \Delta \omega$ . So:

$$\hbar\Delta\omega\times\tau\simeq\hbar\quad\rightarrow\quad\Delta\omega\simeq\frac{1}{\tau}=\Gamma$$

B-1 (0.5 pt)			
$\Gamma = \frac{1}{\tau}$			

B-2. We denote the forward and backward collision rates by  $s_+$  and  $s_-$  respectively. Let us proceed in the atom's frame of reference. Ignoring the terms of the order  $\frac{v^2}{c^2}$ , the Doppler effect can be written in the following form:

$$\omega' = \omega \left( 1 + \frac{v}{c} \right)$$

Taking the atom's velocity in the positive *x*-direction, we have:





 $\omega_{+} = \omega_{\rm L} \left( 1 + \frac{v}{c} \right)$  $\omega_{-} = \omega_{\rm L} \left( 1 - \frac{v}{c} \right)$ 

So:

$$s_{+} = s_{\rm L} + \alpha \left( \omega_{\rm L} \left( 1 + \frac{v}{c} \right) - \omega_{\rm L} \right) = s_{\rm L} + \alpha \omega_{\rm L} \frac{v}{c}$$
$$s_{-} = s_{\rm L} + \alpha \left( \omega_{\rm L} \left( 1 - \frac{v}{c} \right) - \omega_{\rm L} \right) = s_{\rm L} - \alpha \omega_{\rm L} \frac{v}{c}$$

The momentum transfer per unit time from the oncoming photons to the atom is equal to:

$$\pi_+ = s_+ \times (-\hbar k_+)$$

For the backward photons we have:

$$\pi_{-} = s_{-} \times (+\hbar k_{-})$$

Where  $k_{\pm} = \frac{\hbar \omega_{\pm}}{c}$ .

The total momentum transferred to the atom per unit time is equal to:

$$\pi_{+} + \pi_{-} = -2\hbar k_{\rm L} \frac{v}{c} \,\omega_{\rm L} \alpha \left(1 + \frac{s_{\rm L}}{\alpha \omega_{\rm L}}\right)$$

Where with the approximation  $s_{\rm L} \ll \alpha \omega_{\rm L}$ , we will arrive at:

$$\pi_+ + \pi_- = -2\hbar k_{\rm L} \frac{v}{c} \,\omega_{\rm L} \alpha$$

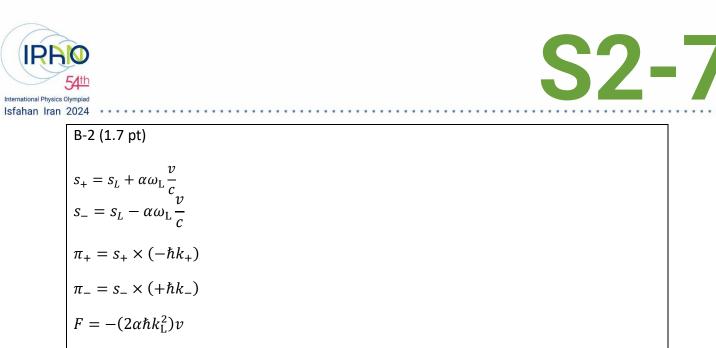
Note that as the atom is heavy, its velocity almost doesn't change after the absorption of the photon. Therefore, there will be almost no Doppler shifting in the re-emitted photon and hence, on average there will be no momentum transfer to the atom during the re-emission process.

The above expression is, in fact, the force. Since v > 0, we have:

$$F = -(2\alpha\hbar k_{\rm L}^2)v$$

The same result holds for v < 0. This is in the atom's reference frame. However, as we have kept only up to the first order in v/c, the same result holds in the lab frame:

$$F = -(2\alpha\hbar k_{\rm L}^2)v$$



B-3. The atom's momentum before the collision is zero. After the collision it will be (assuming the photon's momentum is in the *x*-direction):

$$P_1 = \hbar k_{\rm L}$$

After re-emitting the photon, we may have two equally likely outcomes for the final momentum:

- 1. The photon is emitted in the positive x-direction which causes the atom's momentum to become zero
- 2. The photon is emitted in the negative *x*-direction which causes the atom's momentum to become:  $P_{\rm f} = +2\hbar k_{\rm L}$

Thus, the mean final energy is equal to:

$$\langle E_{\rm f} \rangle = \langle \frac{P_{\rm f}^2}{2m} \rangle = \frac{1}{2} \times 0 + \frac{1}{2} \times \frac{4\hbar^2 k_{\rm L}^2}{2m} = \frac{\hbar^2 k_{\rm L}^2}{m}$$

This process occurs during the time  $\tau$ . So, the input power (the power gained by the atom as a result of this process) is equal to:

$$P_{\rm in} = \frac{\hbar^2 k_{\rm L}^2}{m\tau}$$

B-3 (1.0 pt)  $P_{\rm in} = \frac{\hbar^2 k_{\rm L}^2}{m\tau}$ 

B.4. The output power (the power lost by the atom through collision with laser photons) can be written as:





$$P_{\rm out} = F \cdot v = -2\alpha \hbar k_{\rm L}^2 v^2$$

At equilibrium we should have:

. . . . .

$$P_{\rm out} + P_{\rm in} = 0 \quad \rightarrow \quad \frac{\hbar^2 k_{\rm L}^2}{m\tau} = 2\alpha \hbar k_{\rm L}^2 \overline{v^2} \quad \rightarrow \quad \overline{v^2} = \frac{\hbar \Gamma}{2\alpha m}$$

And the temperature of this system is equal to:

$$\frac{1}{2}m\overline{v^2} = \frac{1}{2}k_{\rm B}T \qquad \rightarrow \qquad T = \frac{\hbar\Gamma}{2\alpha k_{\rm B}}$$

B-4 (0.8 pt)  

$$P_{\text{out}} = -2\alpha\hbar k_{\text{L}}^2 v^2$$

$$\overline{v^2} = \frac{\hbar\Gamma}{2\alpha m}$$

$$T = \frac{\hbar\Gamma}{2\alpha k_{\text{B}}}$$

### B-5. Considering the given data:

$$T = \frac{1\ 055 \times 10^{-34} \text{ J.s}}{2 \times 4 \times 1\ 381 \times 10^{-23} \text{ J/K} \times 5 \times 10^{-9} \text{ s}} = 2 \times 10^{-4} \text{ K}$$

B-5 (0.4 pt)  $T = 2 \times 10^{-4} \text{ K}$ 





# A. A Binary System

A-1. Assume  $a_1$  and  $a_2$ , are respectively, the distances of  $M_1$  and  $M_2$  from the center of mass:

$$\begin{cases} M_1 a_1 = M_2 a_2 \\ a_1 + a_2 = a \end{cases} \rightarrow a_1 = \frac{M_2}{M} a \ , a_2 = \frac{M_1}{M} a \ : M = M_1 + M_2 \end{cases}$$

In the rotating coordinate system, a centrifugal potential has to be added to the gravitational potential of the two masses:

$$U = -\frac{1}{2}\omega^2 r^2 \qquad \omega = \sqrt{\frac{GM}{a^3}}$$
$$\varphi(x, y) = -\frac{GM_1}{\sqrt{(x+a_1)^2 + y^2}} - \frac{GM_2}{\sqrt{(x-a_2)^2 + y^2}} - \frac{1}{2}\omega^2 (x^2 + y^2)$$

$$\varphi(x,y) = -\frac{GM_1}{\sqrt{\left(x + \frac{M_2}{M}a\right)^2 + y^2}} - \frac{GM_2}{\sqrt{\left(x - \frac{M_1}{M}a\right)^2 + y^2}} - \frac{1}{2}\frac{GM}{a^3}(x^2 + y^2)$$

A-1 (1.0 pt)  

$$\varphi(x,y) = -\frac{GM_1}{\sqrt{\left(x + \frac{M_2}{(M_1 + M_2)}a\right)^2 + y^2}} - \frac{GM_2}{\sqrt{\left(x - \frac{M_1}{(M_1 + M_2)}a\right)^2 + y^2}} - \frac{\frac{1}{2}\frac{G(M_1 + M_2)}{a^3}(x^2 + y^2)$$

A-2. We set y = 0 in the previous equation, and obtain:

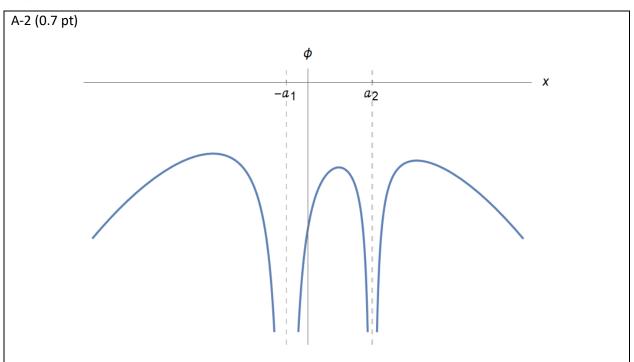
$$\varphi(x,0) = -\frac{GM_1}{\left|x + \frac{M_2}{M}a\right|} - \frac{GM_2}{\left|x - \frac{M_1}{M}a\right|} - \frac{1}{2}\frac{GM}{a^3}x^2$$

We draw the diagram noting that:

- 1. The function has asymptotes at  $x = -a_1$  and  $x = a_2$ , and it tends to  $-\infty$  at both sides of these asymptotes.
- 2. The function has three maxima which are called Lagrange points.
- 3. The function goes to  $-\infty$  for  $x \to \pm \infty$







A-3. Let  $\bar{x} = x/a$ , and denote the Lagrange point in the middle (between  $\bar{x} = 0$  and  $\bar{x} = 0.75$ ) by  $\bar{x}_0$ , we have  $\frac{d\varphi}{d\bar{x}}(\bar{x}_0) = 0$ . Using the given ratios:

$$\varphi(\bar{x},0) = \frac{GM}{a} \left[ -\frac{\frac{3}{4}}{\left(\bar{x}+\frac{1}{4}\right)} + \frac{\frac{1}{4}}{\left(\bar{x}-\frac{3}{4}\right)} - \frac{1}{2} \bar{x}^2 \right]$$

Let  $f(\bar{x}) = \frac{a}{GM} \frac{d\varphi}{d\bar{x}}$ , then we have to solve for  $f(\bar{x}_0) = 0$ . We have f(0) > 0 and f(0.5) < 0, so the answer lies between 0 and 0.5. For the midpoint, we have  $f(\bar{x}_0 = 0.25) > 0$  so  $0.25 < \bar{x}_0 < 0.5$ , so by trial and error:

$$\begin{cases} f(0) > 0\\ f(0.5) < 0 \end{cases} \rightarrow f(0.25) > 0 \rightarrow 0.25 < \bar{x}_0 < 0.5 \rightarrow f(0.375) < 0 \rightarrow \dots \rightarrow 0.358 < \bar{x}_0 < 0.361 \\ \rightarrow f(0.360) > 0 \rightarrow 0.360 < \bar{x}_0 < 0.361 \rightarrow \frac{x_0}{a} = \bar{x}_0 \approx 0.36 \end{cases}$$

So, up to two significant figures the answer is 0.36.

A-3 (0.5 pt)  $\frac{x_0}{a} = 0.36$ 

A-4. The angular momentum of the system is:

$$J = \mu a V = \mu a^{2} \omega = \frac{M_{1}M_{2}}{M} a^{2} \sqrt{\frac{GM}{a^{3}}} = \sqrt{\frac{GM_{1}^{2}M_{2}^{2}}{M}} a^{2}$$





where  $\mu$  is the reduced mass and V is the relative velocity of the two point masses. Taking the logarithm of both sides we'll have:

$$\ln J = \frac{1}{2} \left[ \ln \frac{G}{M} + 2 \ln M_1 + 2 \ln M_2 + \ln a \right]$$

For slowly-varying quantities we'll obtain:

$$\frac{\dot{J}}{J} = \frac{\dot{M}_1}{M_1} + \frac{\dot{M}_2}{M_2} + \frac{1}{2}\frac{\dot{a}}{a}$$

because the total mass is a constant and  $\dot{M}_1 + \dot{M}_2 = 0$ ; therefore:

$$\frac{\dot{a}}{a} = -2\frac{\dot{M}_1}{M_1} \left(1 - \frac{M_1}{M_2}\right) \quad \rightarrow \quad \dot{a} = -2\beta a \left(\frac{1}{M_1} - \frac{1}{M_2}\right)$$

For the period we'll have:

$$P = 2\pi \sqrt{\frac{a^3}{GM}} \to \frac{\dot{P}}{P} = \frac{3}{2}\frac{\dot{a}}{a} = -3\frac{\dot{M}_1}{M_1} \left(1 - \frac{M_1}{M_2}\right) \to \dot{P} = -6\pi \sqrt{\frac{a^3}{GM}}\beta \left(\frac{1}{M_1} - \frac{1}{M_2}\right)$$

A-4 (0.6 pt)  

$$\dot{a} = -2\beta a \left(\frac{1}{M_1} - \frac{1}{M_2}\right)$$

$$\dot{P} = -6\pi \sqrt{\frac{a^3}{GM}} \beta \left(\frac{1}{M_1} - \frac{1}{M_2}\right)$$

A-5. In an infinitesimally thin ring with an inner radius of r and an outer radius r + dr, energy is leaving at a rate of  $-\frac{GM_1\beta}{2r}$  and entering at a rate  $-\frac{GM_1\beta}{2r} + \frac{GM_1\beta}{2r^2}dr$ . For the ring to stay in equilibrium, the excess energy of  $\frac{GM_1\beta}{2r}dr$  per unit time must leave the system as radiation, so:

$$dP = \frac{GM_1\beta}{2r^2}dr = \sigma T^4 2(2\pi r dr) = 4\pi\sigma T^4 dr \rightarrow T = \left(\frac{GM_1\beta}{8\pi\sigma r^3}\right)^{\frac{1}{4}}$$

# A-5 (1.0 pt) $T = \left(\frac{GM_1\beta}{8\pi\sigma r^3}\right)^{\frac{1}{4}}$

A-6. From  $P = 2\pi \sqrt{\frac{a^3}{GM}}$  we'll have:





$$a = \left[\frac{P^2 G (M_{\rm S} + M_{\rm NS})}{4\pi^2}\right]^{\frac{1}{3}}$$

. . . . . .

Using the result of Part A.5, the temperature is:

$$T = \left(\frac{GM_{\rm NS}\beta}{8\pi\sigma r^3}\right)^{\frac{1}{4}} = \left(\frac{500\pi M_{\rm NS}\beta}{\sigma P^2(M_{\rm S} + M_{\rm NS})}\right)^{\frac{1}{4}} = 9 \times 10^3 K$$

#### A-6 (0.5 pt)

 $T = 9 \times 10^3 K$ 

. . . . .

A.7. For the system to remain bounded, the total mechanical energy of the system must be negative:

$$E' = \frac{1}{2}\mu'\nu'^2 - \frac{GM_1'M_2}{a} < 0 \to \nu' < \sqrt{\frac{2G(M_1' + M_2)}{a}}$$

For an isotropic explosion, we would have  $v' = v = \sqrt{\frac{GM}{a}}$  therefore:

$$\sqrt{\frac{G(M_1 + M_2)}{a}} < \sqrt{\frac{2G(M_1' + M_2)}{a}}$$

and:

$$\frac{M_1 - M_2}{2} < M_1$$

A-7 (0.7 pt)  $v'_{\text{max}} = \sqrt{\frac{2G(M'_1 + M_2)}{a}}$  $M'_{1\text{min}} = \frac{M_1 - M_2}{2}$ 

## B. Analysis of the stability of a star

B-1. Using Newton's law of gravity:

$$g = -\frac{4\pi G \int_0^r {r'}^2 \rho dr'}{r^2} \stackrel{\rho \cong \rho_c}{=} -\frac{4\pi G \rho_c r}{3}$$





B-1 (0.2 pt) $g = -\frac{4\pi G \rho_c r}{3}$ 

B-2. Balance of forces for a differential element of volume with a surface area of A and thickness  $\Delta r$  between radii r and  $r + \Delta r$  is as follows:

. . . . . . . . . . . .

. . . .

$$\vec{F} = -\frac{GM(\vec{r})\rho}{r^2} \mathbf{A} \,\Delta r - \Delta p A = 0$$

in which M(r) is the mass of the part of the star confined within the radius r. As  $\Delta r$  is small, we can write:

$$\frac{G\rho}{r^2} \left( \int 4\pi r'^2 \rho(r') dr' \right) = -\frac{dp(r)}{dr} = -K\gamma \rho^{\gamma-1} \frac{d\rho}{dr}$$

Multiplying both sides of the equation by  $\frac{r^2}{4\pi G\rho}$  and taking the derivative once again, we get:

$$\frac{d}{dr}\left[r^2\rho^{\gamma-2}\frac{d\rho}{dr}\right] + \frac{4\pi Gr^2}{K\gamma}\rho(r) = 0$$

B-2 (0.6 pt)  

$$h_1(\rho, r) = r^2 \rho^{\gamma - 2}$$
  
 $h_2(r) = \frac{4\pi G r^2}{K \gamma}$ 

B-3.

$$\begin{split} & [\rho_{\rm c}] = ML^{-3}, \quad [p_{\rm c}] = ML^{-1}T^{-2}, \quad [G] = M^{-1}L^{3}T^{-2} \\ & [G^{l}p_{\rm c}^{m}\rho_{\rm c}^{n}] = (M^{-1}L^{3}T^{-2})^{l}(ML^{-1}T^{-2})^{m}(ML^{-3})^{n} = L \\ & \begin{cases} -l+n+m=0\\ 3l-3n-m=1 \rightarrow \\ -2l-2m=0 \end{cases} \begin{cases} l = -\frac{1}{2} \\ m = \frac{1}{2} \\ n = -1 \end{cases} \rightarrow r_{0} = G^{-\frac{1}{2}}p_{\rm c}^{\frac{1}{2}}p_{\rm c}^{-1} \end{cases} \end{split}$$

B-3 (0.4 pt)  $r_0 = G^{-\frac{1}{2}} p_c^{\frac{1}{2}} \rho_c^{-1}$ 





$$\frac{K\gamma\rho_c^{\gamma-1}}{4\pi Gr_0^2 x^2} \frac{d}{dx} \left[ x^2 u^{\gamma-2} \frac{du}{dx} \right] = -\rho_c u(r)$$
$$\frac{K\gamma\rho_c^{\gamma-2}}{4\pi Gr_0^2 x^2} \frac{d}{dx} \left[ x^2 u^{\gamma-2} \frac{du}{dx} \right] = \frac{\gamma}{4\pi x^2} \frac{d}{dx} \left[ x^2 u^{\gamma-2} \frac{du}{dx} \right] = -u$$
$$\frac{d}{dx} \left[ x^2 u^{\gamma-2} \frac{du}{dx} \right] + \frac{4\pi x^2}{\gamma} u = 0$$

B-4 (0.3 pt)  

$$A_1(u, x) = x^2 u^{\gamma - 2}$$
  
 $A_2(x) = \frac{4\pi x^2}{\gamma}$ 

B-5.

$$\gamma = 2 \rightarrow \frac{d}{dx} \left[ x^2 \frac{du}{dx} \right] = -2\pi x^2 u(x) \rightarrow f''(x) = -2\pi f(x) \rightarrow f(x) = \frac{\sin(\sqrt{2\pi}x)}{\sqrt{2\pi}}$$

B-5 (0.6 pt)  
$$f(x) = \frac{\sin(\sqrt{2\pi}x)}{\sqrt{2\pi}}$$

B.6.

$$\frac{d^2 u}{dx^2} + \frac{(\gamma - 2)}{u} \left(\frac{du}{dx}\right)^2 + \frac{2}{x} \left(\frac{du}{dx}\right) + \frac{4\pi}{\gamma} u^{3-\gamma} = 0$$
$$u'(0) = 0 \quad , \quad \lim_{x \to 0} \frac{u'(x)}{x} = u''(0)$$
$$u''(0) + 2u''(0) + \frac{4\pi}{\gamma} = 0 \quad \to \quad \gamma = -\frac{4\pi}{3u''(0)}$$
$$\gamma \sim [1.64, 1.70]$$

B-6 (0.8 pt)

 $\gamma = [1.64, 1.70]$ 





. . . . . . . . . . . . . . .

. . . . .

B-7 (0.9 pt)

$$\begin{split} \tilde{g} &\simeq g(1-2\epsilon) \\ \tilde{\rho} &\simeq \rho(1-3\epsilon) \end{split}$$

. . . . . . . .

B-8. we have

$$\frac{\partial \tilde{p}}{\partial \tilde{r}} = \tilde{\rho} \big( \tilde{g} - \ddot{r} \big)$$

And

 $\tilde{p} = K \tilde{\rho}^{\gamma}$ 

So:

$$\ddot{\tilde{r}} = \tilde{g} - \frac{\left(\frac{\partial \tilde{p}}{\partial \tilde{r}}\right)}{\tilde{\rho}} = \tilde{g} - K\gamma \tilde{\rho}^{\gamma-2} \frac{\partial \tilde{\rho}}{\partial \tilde{r}}$$

B-8 (0.6 pt)  $\frac{d^2 \tilde{r}}{dt^2} = \tilde{g} - K\gamma \tilde{\rho}^{\gamma-2} \frac{\partial \tilde{\rho}}{\partial \tilde{r}}$ 

B.9. Using of the results in B.7 and B.8, we have:

$$\begin{aligned} \frac{d^2\tilde{r}}{dt^2} &= \ddot{\tilde{r}} = \tilde{g} - K\gamma\tilde{\rho}^{\gamma-2}\frac{\partial\tilde{\rho}}{\partial\tilde{r}} = g(1-2\epsilon) - K\gamma\rho^{\gamma-2}\frac{\partial\rho}{\partial r}\left(\frac{(1-3\epsilon)^{\gamma-1}}{(1+\epsilon)}\right) \\ &= g(1-2\epsilon) - K\gamma\rho^{\gamma-2}\frac{\partial\rho}{\partial r}(1-3(\gamma-1)\epsilon-\epsilon) \end{aligned}$$

Equilibrium requires:

$$g - K\gamma \rho^{\gamma-2} \frac{\partial \rho}{\partial r} = 0 \Rightarrow K\gamma \rho^{\gamma-2} \frac{\partial \rho}{\partial r} = g$$

therefore:

$$\ddot{r} = r\ddot{\epsilon} = g(1-2\epsilon) - g(1-3(\gamma-1)\epsilon - \epsilon) = g(3\gamma-4)\epsilon$$



and:

. .

$$\ddot{\epsilon} = \frac{g}{r}(3\gamma - 4)\epsilon$$
$$\ddot{\epsilon} = -\frac{4\pi G\rho_{\rm c}}{3}(3\gamma - 4)\epsilon$$

Stability requires that:

$$3\gamma - 4 > 0 \Rightarrow \gamma > \frac{4}{3}$$

and the angular velocity of the oscillations will be:

$$\omega = \sqrt{\frac{4\pi G\rho_{\rm c}}{3}(3\gamma - 4)}$$

B-9 (0.6 pt)  

$$\ddot{\epsilon} = -\frac{4\pi G \rho_c}{3} (3\gamma - 4)\epsilon$$

$$\gamma_{\min} = \frac{4}{3}$$

$$\omega = \sqrt{\frac{4\pi G \rho_c}{3} (3\gamma - 4)}$$







### Marking Scheme Q1 (10 points)

Part A (3.0 pt) If the final answer is written then the complete point will be achieved

A-1	$r = (R_{S})^{2} (0, 1, 1)$	0.6 pt
	$S_0 = \sigma T_{\rm S}^4 \cdot \left(\frac{R_{\rm S}}{d}\right)^2 $ (0.4pt),	
	[Realizing energy conservation (0.1pt)]	
	Numerical value of $S_0 = 1.35 \times 10^3 \text{ W/m}^2$ (0.2pt)	
	[more than 4 significant figures (0.1pt)]	
A-2	$T_{\rm E} = \left(\frac{S_0}{4\sigma}\right)^{\frac{1}{4}} = \sqrt{\frac{R_{\rm S}}{2d}} T_{\rm S} \ (0.4  {\rm pt}),$	0.6 pt
	[realizing energy balance (0.1pt)]	
	Numerical value of $T_{\rm E} = 278$ K (0.2pt)	
	[more than 4 significant figures (0.1pt)]	
A-3	$f(x) = 5(1 - e^{-x}) - x$	0.4 pt
A-4	$x_{\rm m} = \{4.96, 4.97\}$ (0.3 pt),	0.4 pt
	[more than 4 significant figures (0.2pt)]	
	Numerical value of $b = [2.89, 2.90] \times 10^6$ nm. K (0.1 pt)	
	[more than 4 significant figures (0.1pt)]	
A-5	$\lambda_{\rm max}^{\rm Sun} = [5.01, 5.02] \times 10^2  \rm nm(0.1  pt),$	0.2 pt
	$\lambda_{\text{max}}^{\text{Earth}} = 1.04 \times 10^4 \text{ nm}(0.1 \text{ pt})$	
	[more than 4 significant figures (0.1pt)]	
A-6	$\gamma = \left(\frac{d}{R_{\rm S}}\right)^2 \times \left(\frac{T_{\rm E}}{T_{\rm S}}\right)^5 = \left(\frac{\lambda_{\rm S}}{\lambda_{\rm E}}\right)^5 \times \left(\frac{d}{R_{\rm S}}\right)^2 \ (0.6 \text{ pt}),$	0.8 pt
	[realizing $\tilde{u}_{\rm S} = \left(\frac{R_{\rm S}}{d}\right)^2 u_{\rm S}(\lambda)(0.3 {\rm pt})$ ]	
	Numerical value of $\gamma = [1.20, 1.21] \times 10^{-2}$ (0.2 pt)	
	[more than 4 significant figures (0.1pt)]	

Part B (7.0 pt)

B-1	1	1.0 pt
D-1	$\left(\left(1-r_{A}\right)\frac{S_{0}}{I}\right)^{\overline{4}}$	1.0 pt
	$T_A = \left(\frac{(1-r_A)\frac{S_0}{4}}{\sigma}\right)^{\overline{4}}$	
	$T_{\rm E} = \left(\frac{(1-r_{\rm A})\frac{S_0}{2}}{\sigma}\right)^{\frac{1}{4}}$	
	Two correct expressions (0.8 pt)	
	[One correct expression (0.6 pt)]	
	[no correct expression: for each energy balance relation (0.2pt)]	
	Numerical value of $T_A = 2.58 \times 10^2$ K (0.1 pt)	
	Numerical value of $T_{\rm E} = 3.07 \times 10^2$ K (0.1 pt)	
	[more than 4 significant figures (0.1pt)]	
B-2	$\alpha = r_{\rm A} + \frac{(1 - r_{\rm A})^2 r_{\rm E}}{1 - r_{\rm A} r_{\rm E}}  (1.4  \text{pt})$	1.6 pt
	$[\tilde{S}_0 = r_A S_0 (0.1 \text{ pt})]$	
	$\begin{bmatrix} \tilde{S}_0 = r_A S_0 \ (0.1 \text{ pt}) \\ \tilde{S}_1 = (1 - r_A)^2 r_E S_0 = \frac{(1 - r_A)^2}{r_A} r_E \tilde{S}_0 \ (0.3 \text{ pt}) \end{bmatrix}$	





	$\tilde{S}_n = \frac{\tilde{S}_{n-1}}{1 - r_A} r_A r_E \times (1 - r_A) = r_A r_E \tilde{S}_{n-1} = (r_A r_E)^{n-1} \tilde{S}_1  (0.5 \text{ pt})$	
	$\tilde{S} = \sum_{n=0}^{\infty} \tilde{S}_n = \tilde{S}_0 + \tilde{S}_1 \sum_{n=1}^{\infty} (r_A r_E)^{n-1}$ (0.3 pt)]	
	Numerical value of $\alpha = 3.13 \times 10^{-1}$ (0.2pt)	
	[more than 4 significant figures (0.1pt)]	
B-3	$T_{\rm E} = \left[\frac{(1-\alpha)}{2\sigma(2-\epsilon)}S_0\right]^{\frac{1}{4}}  (0.6 {\rm pt})$	1.0 pt
	Numerical value of $\epsilon = [8.07, 8.11] \times 10^{-1} (0.4 \text{ pt})$	
	[wrong numerical value: correct expression for $\epsilon$ (0.2pt)] [more than 4 significant figures (0.3pt)]	
B-4	$\frac{dT_{\rm E}}{d\epsilon} = \frac{1}{4} \left[ \frac{(1-\alpha)S_0}{2\sigma(2-\epsilon)} \right]^{\frac{1}{4}} \frac{1}{(2-\epsilon)} (0.6 \text{ pt}),$	0.8 pt
	Numerical value of $\delta T_{\rm E} = [4.87, 4.92] \times 10^{-1}$ K (0.2pt)	
	[more than 4 significant figures (0.1pt)]	
B-5	$\epsilon = \frac{\sigma T_{\rm E}^4 - (1 - \alpha) \frac{S_0}{4}}{\sigma (T_{\rm E}^4 - T_{\rm A}^4)}$ (0.6pt)	1.6 pt
	$k = \frac{(2T_{\rm A}^4 - T_{\rm E}^4) \times \left[\sigma T_{\rm E}^4 - (1 - \alpha) \frac{S_0}{4}\right]}{(T_{\rm E}^4 - T_{\rm A}^4) \times (T_{\rm E} - T_{\rm A})}  (0.6 \text{pt})$	
	[Correct relations for balance of energy (0.3+0.3 pt)]	
	Numerical value of $\epsilon = [8.47, 8.52] \times 10^{-1}$ (0.2pt)	
	Numerical value of $k = [3.57, 3.66] \times 10^{-1}$ W/m <sup>2</sup> K (0.2pt)	
	[more than 4 significant figures for each one (0.1pt)]	
B-6	(a) (0.4+0.4)	1.0 pt
	$\int \epsilon \left[ \frac{1}{T_{\rm E} - T_{\rm A}} + \frac{4T_{\rm E}^3}{2T_{\rm A}^4 - T_{\rm E}^4} \right] \frac{dT_{\rm E}}{d\epsilon} = 1 + \epsilon \left[ \frac{8T_{\rm A}^3}{2T_{\rm A}^4 - T_{\rm E}^4} + \frac{1}{T_{\rm E} - T_{\rm A}} \right] \frac{dT_{\rm A}}{d\epsilon} $ (0.0 mt)	
	$\begin{cases} \epsilon \left[ \frac{1}{T_{\rm E} - T_{\rm A}} + \frac{4T_{\rm E}^3}{2T_{\rm A}^4 - T_{\rm E}^4} \right] \frac{dT_{\rm E}}{d\epsilon} = 1 + \epsilon \left[ \frac{8T_{\rm A}^3}{2T_{\rm A}^4 - T_{\rm E}^4} + \frac{1}{T_{\rm E} - T_{\rm A}} \right] \frac{dT_{\rm A}}{d\epsilon} \\ 1 + \epsilon \left[ \frac{4T_{\rm E}^3}{T_{\rm E}^4 - T_{\rm A}^4} - \frac{4\sigma T_{\rm E}^3}{\sigma T_{\rm E}^4 - (1 - \alpha) \frac{S_0}{4}} \right] \frac{dT_{\rm E}}{d\epsilon} = \frac{4T_{\rm A}^3}{T_{\rm E}^4 - T_{\rm A}^4} \epsilon \frac{dT_{\rm A}}{d\epsilon} \end{cases} $ (0.6 pt)	
	(b) $\delta T_{\rm E} = [5.21, 5.28] \times 10^{-1} {\rm K}$ (0.2pt)	
	[more than 4 significant figures for each one (0.1pt)]	





### Marking Scheme Q2 (10 points)

Part A (5.6 pt)

A-1		
(a)	$\vec{E}(x, y, z) = \frac{-\lambda x}{4\epsilon_0 R^2} \hat{x} + \frac{-\lambda y}{4\epsilon_0 R^2} \hat{y} + \frac{\lambda z}{2\epsilon_0 R^2} \hat{z}  (1.0 \text{ pt})$	
	[z-component (0.5 pt), x- and y- components (0.5 pt), wrong	1.5 pt
	coefficient for each component (-0.1 pt), wrong sign for each	
	component (-0.2 pt)]	
(b)	$\omega_x = \omega_y = \sqrt{\frac{Q\lambda}{4\epsilon_0 R^2 m}}  (0.5 \text{ pt})$ $a = \frac{Qu}{2\epsilon_0 R^2 m \Omega^2}  (0.2 \text{ pt})$	
A-2	$a = \frac{Qu}{22 P^2 m Q^2}  (0.2 \text{ pt})$	
	$2\epsilon_0 R^2 m \Omega^2$	0.4 pt
	$k = \sqrt{\frac{Q\lambda_0}{2\epsilon_0 R^2 m}}  (0.2 \text{ pt})$	
A-3		
	$\ddot{q} = pa\Omega^2 \cos \Omega t \ (1.0 \text{ pt})$	
	$\begin{bmatrix} 1 \\ 1 \\ 2 \end{bmatrix}$	
	[each of the 3 approximations (0.3 pt), the final equation (0.1pt)]	
	$q = -pa\cos\Omega t \ (0.8 \text{ pt})$	1.8 pt
	[general solution (0.4 pt), fixing the free parameters in the general	
	solution each (0.2 pt)]	
A-4	$\ddot{p}(t) = \left(k^2 - \frac{a^2 \Omega^2}{2}\right) p$ (1.2 pt)	
	[Correct approach (0.6 pt), Correct result (0.6 pt)]	
	$\Omega > \sqrt{2} \frac{k}{a}  (0.3 \text{ pt})$	1.5 pt
A-5	$k = 2 \times 10^5 \text{ rad/s} (0.2 \text{ pt})$	
		0.4 pt
	$\Omega_{\min} \simeq 7 \times 10^6 \text{ rad/s} (0.2 \text{ pt})$	
	[ inappropriate number of significant figures (-0.1 pt)]	

### Part B (4.4 pt)

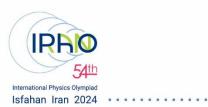
B-1	$\Gamma = \frac{1}{\tau} (0.5 \text{ pt})$	
	[Answers with different numerical coefficients should be considered as	0.5 pt
	correct answers]	





B-2	$s_{+} = s_{\rm L} + \alpha \omega_{\rm L} \frac{v}{c}  (0.5 \text{ pt})$	
	$s_{-} = s_{\rm L} - \alpha \omega_{\rm L} \frac{v}{c}  (0.5 \text{ pt})$	
	[correct Doppler shift each (0.3 pt), final answer each (0.2 pt)]	1 7 nt
	$\pi_{+} = s_{+} \times (-\hbar k_{+})$ (0.1 pt)	1.7 pt
	$\pi_{-} = s_{-} \times (+\hbar k_{-})$ (0.1 pt)	
	$F = -(2\alpha\hbar k_{\rm L}^2)v \ (0.5{\rm pt})$	
B-3	$F = -(2\alpha\hbar k_{\rm L}^2)\nu \ (0.5 \text{pt})$ $\begin{cases} p = 0 \\ p = +2\hbar k_{\rm L} \ (0.5 \text{pt}) \end{cases}$	
	[one correct answer (0.3 pt)]	1.0 pt
	$P_{\rm in} = \frac{\hbar^2 k_{\rm L}^2}{m\tau}  (0.5 \text{ pt})$	
B-4	$P_{\rm out} = -2\alpha \hbar k_{\rm L}^2 v^2 \ (0.3 \ {\rm pt})$	
	$\overline{v^2} = \frac{\hbar\Gamma}{2\alpha m} (0.3 \text{ pt})$ $T = \frac{\hbar\Gamma}{2\alpha k_B} (0.2 \text{ pt})$	
	$T = \frac{\hbar\Gamma}{2\alpha k_{\rm B}} (0.2  {\rm pt})$	0.8 pt
	[Answers with different numerical coefficients should be considered as	
	correct answers]	
B-5	$T = 2 \times 10^{-4} \mathrm{K} (0.4 \mathrm{pt})$	
	[according to the coefficient used in the part B.4, the resulting temperature might be different.]	0.4 pt

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Marking Scheme Q3 (10 points)

### Part A (5.0 pt)

	$GM_1$ $GM_2$ $1G(M_1 + M_2)$	
A-1	$\Phi(x,y) = -\frac{GM_1}{\sqrt{\left(x + \frac{M_2}{(M_1 + M_2)}a\right)^2 + y^2}} - \frac{GM_2}{\sqrt{\left(x - \frac{M_1}{(M_1 + M_2)}a\right)^2 + y^2}} - \frac{\frac{1}{2}\frac{G(M_1 + M_2)}{a^3}(x^2 + y^2)}{a^3}$ [Gravitational part (0.5 pt)] [Centrifugal part (0.5 pt)]	1.0 pt
A-2	[Correct behavior at infinity (0.1 pt)] [Three maximums (0.3 pt)] [Two vertical asymptotes (0.3 pt)]	0.7 pt
A-3	$\frac{x_0}{a} = 0.36$ [In case of obtaining correct equation but not solving it (0.2 pt)] [Obtaining the numerical result with one decimal figure (0.3 pt)]	0.5 pt
	$\dot{a} = -2\beta a \left(\frac{1}{M_1} - \frac{1}{M_2}\right) (0.3 \text{ pt})$ $\dot{P} = -6\pi \sqrt{\frac{a^3}{GM}} \beta \left(\frac{1}{M_1} - \frac{1}{M_2}\right) (0.3 \text{ pt})$ [Only correct approach (conservation of momentum) (0.2 pt)]	0.6 pt
A-5	$T = \left(\frac{GM_1\beta}{8\pi\sigma r^3}\right)^{\frac{1}{4}}$ [Correct approach (Energy relation) (0.5 pt)] [Correct solution (0.5 pt)]	1.0 pt
A-6	$a = \left[\frac{P^2 G(M_{\rm S} + M_{\rm NS})}{4\pi^2}\right]^{\frac{1}{3}} (0.3 \text{ pt})$ $T = \left(\frac{500\pi M_{\rm NS}\beta}{\sigma P^2 (M_{\rm S} + M_{\rm NS})}\right)^{\frac{1}{4}} (0.1 \text{ pt})$ $T = 9 \times 10^3 \text{ K (0.1 pt)}$ [If the final answer for T is correct the complete pt will be given]	0.5 pt
A-7	$E' = \frac{1}{2}\mu'v'^2 - \frac{GM'_1M_2}{a} < 0  (0.2 \text{ pt})$ $v'_{max} = \sqrt{\frac{2G(M'_1 + M_2)}{a}}  (0.2 \text{ pt})$ $v' = v  (0.2 \text{ pt})$ $M'_{1min} = \frac{M_1 - M_2}{2}  (0.1 \text{ pt})$	0.7 pt





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Part B (5.0 pt)

B-1	$g = -\frac{4\pi G \rho_{\rm c} r}{3}$	0.2 pt
B-2	$h_1(\rho, r) = r^2 \rho^{\gamma - 2}$ $h_2(r) = \frac{4\pi G r^2}{K\gamma}$	0.6 pt
	$[\vec{F} = -\frac{GM(\vec{r})\rho}{r^2} A \Delta r - \Delta pA = 0  (0.3 \text{ pt})]$ $r_0 = G^{-\frac{1}{2}} p_c^{\frac{1}{2}} \rho_c^{-1}$	
B-3	$r_0 = G^{-\frac{1}{2}} p_c^{\frac{1}{2}} \rho_c^{-1}$	0.4 pt
	$A_1(u, x) = x^2 u^{\gamma - 2}$ $A_2(x) = \frac{4\pi x^2}{\gamma}$	
B-4	$A_2(x) = \frac{4\pi x^2}{\gamma}$	0.3 pt
	The answer would be correct up to a constant coefficient	
B-5	$f(x) = A \sin(\sqrt{2\pi}x) + B\cos(\sqrt{2\pi}x) $ (0.3 pt) $A = \frac{1}{\sqrt{2\pi}} (0.2 \text{ pt}) \& B = 0 $ (0.1 pt)	0.6 pt
	$u'(0) = 0 (0.1 \text{ pt})$ $\lim_{x \to 0} \frac{u'(x)}{x} = u''(0) (0.4 \text{ pt})$ $\gamma = -\frac{4\pi}{3u''(0)} (0.2 \text{ pt})$ $\gamma \sim 1.66 (0.1 \text{ pt})$	0.8 pt
B-7	$\begin{split} \tilde{\rho} &\simeq \rho (1 - 3\epsilon) \text{ (0.6 pt)} \\ [\tilde{\rho} &= \rho (1 + \epsilon)^{-3} \text{ (0.4 pt)}] \\ \tilde{g} &\simeq g (1 - 2\epsilon) \text{ (0.3 pt)} \\ [\tilde{g} &= g (1 + \epsilon)^{-2} \text{ (0.2 pt)}] \end{split}$	0.9 pt
B-8	$\begin{bmatrix} \tilde{g} = g(1+\epsilon)^{-2}(0.2\text{pt}) \end{bmatrix}$ $\ddot{\tilde{r}} = \tilde{g} - k\gamma \tilde{\rho}^{\gamma-2} \frac{\partial \tilde{\rho}}{\partial \tilde{r}}$	0.6 pt
B-9	$\ddot{\epsilon} = -\frac{4\pi G \rho_c}{3} (3\gamma - 4)\epsilon  (0.4 \text{ pt})$ $\gamma_{\min} = \frac{4}{3}  (0.1 \text{ pt})$ $\omega = \sqrt{\frac{4\pi G \rho_c}{3} (3\gamma - 4)}  (0.1 \text{ pt})$	0.6 pt